

Programming Guide

for Crude Oil Systems

Revision: 1.1 Last Updated: Feb. 5, 2024

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FINCH II Programming



SensorLink

SensorLink is a desktop software application that Titan Logix created for programming and configuring your **TD100 System hardware** installed on your vehicles. SensorLink allows you to create and modify your strapping tables and program your hardware based on specific operational parameters and tank specifications. SensorLink can be downloaded from Titan Logix's website.

Titan Logix's Transmitter and FINCH II display must be connected to the computer that has the latest version of SensorLink installed, Titan Logix's desktop application, to complete the programing steps.

1 Go to <u>www.titanlogix.com/downloads</u> to download the latest version of SensorLink onto your computer.

Note:
SensorLink will only work on a PC computer.

2 After this is installed, double-click the **SensorLink icon** on your desktop.

The SensorLink home page appears with the Transmitter and FINCH menu options on the left panel.



- Select FINCH II option on the left panel to program your FINCH II 6W.
- Select **TD100** option on the left panel to program your TD100 Transmitter.

Strapping Table Setup

Probe Settings

Step 1: Probe Settings Probe Type	
Coaxial Probe	~
Detection Mode ?	
Performance	Ŷ
Depth Units	
Inches	×
Volume Units	
Gallons (US)	~

- **1** Select the appropriate values from the drop-down menus on the left panel:
 - Probe Type
 - Detection Mode
 - Depth Units
 - Volume Units

The strapping table in the middle of the screen is now ready to be filled out. The first row is added once these drop-down menus are filled out.

Strapping Table Configuration

The example below highlights the different sections that are required to build out your strapping table. The required fields become active once the section above is filled out. The active drop-down field name appears in red to indicate your next step.

Make sure your strapping table includes the exact measurements provided by the tank manufacturer.

Step 1: Probe Settings Probe Type 1		3		Steps 3, 4, and 5	
Coavial Probe	New Table				
	Depth (in)	Volume (US gal)	Information		Spill Riser
Detection Mode	0.00	0.000	4mA Point, Bottom of Sump	A 1	Тор НН
	4.00	0.000	Top of Sump		
Performance ~	4.50	0.500	210		
Depth Units	5.00	1.000			lank
	6.00	2.000			
Inches	7.00	3.000			
Volume Units	8.00	4.000			Bottom
Volume onits	8.50	4.500	нн — 7		
Gallons (US) Y	9.00	5.000			Sump
Step 2: Strapping Table	9.50	5.500			Tank Spill HH 2Lo Sump Total Offset
Fill in table on right	10.00	6.000			10.000 4.000 7.000 4.500 4.000 ? 1.500 ?
Fill in table on right	10.50	6.500			
Edit	11.00	7.000			Graph of Strapping Table
	11.50	7.500	Spill Level		- Volume 🛑 Spill 😑 HH 🚫 4mA 💭 20mA
Step 3: Offset Measurement	12.00	8.000			
	13.00	9.000			10.000
Offset Measurement	14.00	10.000	Actual Tank Top		
Step 4: Alarm Settings	15.50	10,000	20mA Point, Probe Tank Top		****
Soil Alarm Lovel					8.000
4.0 in (7.5 US gal)		8			(res com
Spill Alarm Reset					0000 (13
Auto-Clear					³ 4.000
HH Level7					
Depth (in) , Volume (US gal)	1				2.000
Step 5: Display Settings	1				0.0000
Display Resolution 8					0 Depth of Fluid (in) 10
3 Digits v					
Optional Steps 9					
Set Sump					
Set 4-20mA Points					

	Section	Description	Reference
1	Probe Type	The type of probe installed in your tank.	Page 5
2	Detection Mode	 The Performance Detection Mode is recommended for new installations. The Standard Detection Mode is only recommended when it is necessary to mimic TD80 behaviour. 	Page 5
3	Depth and Volume Units	The Depth and Volume units used in your strapping table. These values will update in the Depth and Volume columns in the middle of the screen based on the selection made in these drop-down menus.	Page 5
4	Strapping Table	The depth and volume measurements provided by the tank manufacture.	Page 5
5	Offset Measurement	The Tank Thickness and Probe Offset values measured when installing the probe.	Page 7
6	Spill Alarm	 This is only required to fill out for Coaxial Probes. The Dual-Rod Probe spill levels are automatically set for you and are not able to be changed from here. 	Page 7
7	HH Level	The High-High Depth and Volume level.	Page 7
8	Display Resolution	The number of Digits used for your maximum volume measurement value.	Page 8
9	Optional Settings	This is where you would set the Sump Value and 4-20mA Points , if required.	Page 9

1 Fill out the strapping table based on one of the following options:

- Importing through a CSV file (Page 11)
- Manually adding through SensorLink (Page 13)
- 2 After the strapping table is properly filled out, click the **Done** button on the left panel.

Step 1: Probe Settings Probe Type			+ 🗙	csv	Steps 1 and 2
Coaxial Probe	~	New Table Fill Table	Add Row Delete Row In	mport CSV	
		Depth (in)	Volume (US gal)	Information	
Detection Mode ?		0.00	0.000		
		1.00	1.000		
Performance	×	2.00	2.000		
Depth Units		3.00	3.000		
Inchas	~	4.00	4.000		
inches		5.00	5.000		
Volume Units		6.00	6.000		
		7.00	7.000		
Gallons (US)		8.00	8.000		
Stan 2: Stranning Table		9.00	9.000		
Step 2. Strapping Table		10.00	10.000		
Fill In the on right		11.50	10.000		
Done					

The strapping table and the diagram to the right of the table automatically updates with the tank specifications filled out.



Offset Measurement Setup



1 Click the **Offset Measurement** button from the left panel.

The Offset Measurement dialog box appears.

2 Fill in the Tank Thickness and Probe Offset values and units from the drop-down menus.

```
Note:
```

These are the measurements captured in the TD100 System Installation Quick Reference Guide.

3 The total offset value is automatically calculated based on the following formula:

TOTAL OFFSET = TANK THICKNESS + PROBE OFFSET

Tip:

Make sure your total offset is not greater than the Spill level.

4 Click OK.

You are taken back to the main screen.

Configuring Alarm Settings

The Spill Alarm configuration for a **Dual-Rod Probe** is pre-selected based on the settings defined in your strapping table. You are **not** able to make any changes to Spill Alarm drop-down values if you have a dual-rod probe.



1 If using a **Coaxial Probe**, complete the Spill Alarm fields. If using a **Dual-Rod Probe**, skip this step and go to **step 2**.

Menu	Description						
	The Spill Alarm lev	e Spill Alarm level is set based on the detection mode selected above.					
	Performance	Berformance Detection Mode: Select from a range between 4 to 17 inches					
Spill Alarm Level		• Fertormance Detection mode: Select from a range Setween 4 to 17 menes.					
	 Standard Det probe nut. 	 Standard Detection Mode: Use the measurement from the bottom edge of the probe nut. 					
	Select one of the f	ollowing option	s from the drop-	down menu:			
Spill Alarm Reset	• Auto-Clear						
Spin Alarm Reset	Auto-Clear						
	 Band-Clear 						
		Depth (in)	Volume (US gal)	Information			
		0.00	0.000	4mA Point, Bottom of Sump	1		
		4.00	0.000	Top of Sump	1		
Step 4: Alarm Settings		4.50	0.500	2Lo			
		5.00	1.000				
		6.00	2.000				
Step 4. Alarit.	securigs	7.00	3.000				
Spill Alarm Lev	el	8.00	4.000				
4.0 in (7.5 US	gal) v	0.10	4.500	нн	\mathbf{P}		
		9.00	5,000		-		
		9.50	5.500		-		
Spill Alarm Reset ?		10.00	6.000		-		
have floor	10.50	6.500		-			
Auto-Clear		11.00	7.000	Call Land			
		12.00	7.500	Spill Level			
		12.00	0.000		-		
Departany ,	Containe (congui)	14.00	10.000	Actual Tank Ton	-		
8.50 ,	4.50	15.50	10.000	20mA Point Prohe Tank Ton	-		
		10.00	10.000	Louis round, riobe lank lop	1		

2 Fill in the High-High level in the Depth and Volume fields and press [Enter] to update the strapping table.

Tip:

The HH alarm threshold must be above 2Lo and at least 2 inches below the spill level.

Setting the Display Settings

It is recommended to configure your volume measurements to use the 5-digit reading on the FINCH II – 6W display.

For example, if the maximum volume of your tank is **80 barrels**, then set the display resolution to 3 decimal places. This will display as **80.000** on the FINCH II - 6W display as well as on the strapping table.

1 Select the number of digits to use for your maximum volume measurement from the Display Resolution drop-down menu.

The Volume column in the strapping table is updated based on your selection.

	Depth (in)	Volume (US gal)	Information
	0.00	0.000	4mA Point, Bottom of Sump
	4.00	0.000	Top of Sump
	4.50	0.500	2Lo
	5.00	1.000	
	6.00	2.000	
	7.00	3.000	
	8.00	4.000	
	8.50	4.500	HH
	9.00	5.000	
	9.50	5.500	
	10.00	6.000	
	10.50	6.500	
	11.00	7.000	
	11.50	7.500	Spill Level
p 5: Display Settings	12.00	8.000	
play Resolution	13.00	9.000	
Disite	14.00	10.000	Actual Tank Top
Digits	15.50	0000	20mA Point, Probe Tank Top

(Optional) Sump and 4-20mA Settings

These steps are only required if you have a sump on your tank and if your installation includes a 4-20mA current loop interface. Otherwise, skip this section and go to **Saving your Strapping Table (Page 10)**.

Setting the Sump Value

Ste Dis

1 Click the Set Sump button under the Optional Steps section in the left panel.

The Set Sump dialog box appears.



2 Fill out the **Sump** value as applicable to the installation.

Tip:	
The sump value cannot be less than zero.	

3 Click OK.

You are now taken back to the main window. The strapping table updates with the new information.

Setting the 4-20mA Points

1 Click the **Set 4-20mA Points** button below the **Optional Steps** section in the left panel.

The Set 4-20mA Points dialogue box appears.



2 Fill out the 20mA Point and 4mA Point values.

Tip:

- The 4mA and 20mA points cannot be less than zero.
- The 4mA point must be set **below** the 20mA point.
- 3 Click OK.

You are now taken back to the main window. The strapping table updates with the new information.

Saving the Strapping Table

It is important to save your strapping table data for reference or troubleshooting purposes.

1 Prior to saving your file, click Verify from the top menu bar to ensure there are no errors in your strapping table.

🚹 Home	File	1 Program	👱 Read	Verify	Convert Units 💰	Firm
Step 1: Probe Settings Probe Type	5				Steps 3, 4, and 5	
Coaxial Probe		New Table				
		Depth (in)	Volume (US gal)	Information		
Detection Mode ?		0.00	0.000	4mA Point		~
		1.00	1.000			
Performance		2.00	2.000			
Depth Units		3.00	3.000			
Inchos		4.00	4.000	_		
inches		4.50	4.500	2Lo		
Volumo Unito		5.00	5.000			

2 If everything is configured correctly, a verification window appears letting you know that the strapping table is configured correctly.

Note:

A dialogue box appears indicating the specific errors to address before continuing. Make any necessary adjustments and click **Verify** again to ensure all the errors have been addressed.

3 Once everything is verified, click **File > Save File** from the top menu bar.

🚹 Home	File 1 Program	👱 Read 🥑 Verify
Step 1: Probe Setting Probe Type	Save File	
Coaxial Probe	Save to Hex File Import Hex File	me (US gal) Information
Detection Mode ?	Import CSV File	0 4mA Point
Performance	Help	0
Dopth Units	13.00	3.000

The Save As window appears.

- 4 Choose the desired location to save the strapping table to on your computer.
- 5 Fill out a File name (as per your organization's convention) for the strapping table and click Save.

Note:

Notice that the file type is set to ***.stb** which is the strapping table file extension.

$\rightarrow \rightarrow \uparrow \uparrow$	A > Home	× C	Search Home	م
		0		,
Organize 🝷			≣ •	?
A Home	Name		Date modified	Ту
	~ Quick access			
	E Desktop		2023-06-30 11:28 AM	Sy
📃 Desktop 🛛 🖈	↓ Downloads		2023-07-10 1:05 PM	Sy
🛓 Downloads 🏓		_	2023-07-10 12:58 PM	Fi
File name:				
Save as type: St	rapping Tables (*.stb)			

Adding Your Strapping Table Data

You can add the manufacturer's depth and volume measurements for your tank by importing this through a CSV file or manually adding it inside SensorLink.

After completing this step, go back to the Configuring Probe Settings (Page 5) section and proceed with step 3.

Option 1: Importing through a CSV File

It is sometimes easier to build out your strapping table outside of SensorLink and import the information afterwards.

1 Create a two-column table that includes the depth and volume values from the manufacturer strapping table.

Depth (in)	Volume (US gal)
0.00	0.00
1.00	5.00
2.00	10.00
3.00	15.00
4.00	20.00
5.00	25.00
6.00	30.00
7.00	35.00
8.00	40.00
9.00	45.00
10.00	50.00
11.00	55.00
12.00	60.00

- 2 Save this file as a *.csv file.
- **3** From SensorLink, click **File > Import CSV File** from the top menu bar.



The **Open** dialogue window appears.

- 4 Navigate to where you saved your ***.csv file** and select the file.
- 5 Click **Open** to import this into SensorLink.

Tip:

Make sure the *.csv file is closed out before importing it into SensorLink.

The Depth and Volume information added in the .csv file is now added to the strapping table inside of SensorLink.



Option 2: Manually Adding through SensorLink

You can manually add the depth and volume information for your strapping table right inside of SensorLink as well.



1 Use the icons in the strapping table section to fill out your **Depth** and **Volume** values of your strapping table.

Icon Name	Description
New Table	This will clear the existing strapping table. Make sure to save your information before clicking this icon if you do not want to lose your data.
Fill Table	The Fill Depth Values dialogue box appears to allow you to easily build out your strapping table based on your start and end values for the depth and volume of your tank, and how much the values increment by.
Add Row	Adds an additional row to your table.
Delete Row	Deletes the selected row from your table.

Viewing Your Strapping Table Configurations

1 From SensorLink, click **File > Import File** from the top menu bar.

🔶 Home	File	1 Program		👱 Read			Verify
Step 1: Probe Settings Probe Type	0	Save File Import File	>				
Coaxial Probe		Save to Hex File Import Hex File		me (US gal)	Inform	nation	
Detection Mode ?		Import CSV File		<mark>)</mark> D	4mA Poi	nt	
Performance		Help		0			
Depth Units		3.00	3.00	0 0			

The **Open** dialogue window appears.

- 2 Navigate to where you saved your .stb (strapping table) file and select the file.
- **3** Click **Open** to import this into SensorLink.

TD100 Transmitter Programming

Titan Logix provides an SV Bus Programming Kit as well as a USB serial port adapter for you to use to program your TD100 Transmitter.

The diagram below shows the **SV Bus Programming Kit** and the connection between the **TD100 Transmitter** and your **computer**.



Connecting to the TD100 Transmitter

Use one of the two options listed below to connect Titan Logix's SV Bus Programming Kit to your TD100 Transmitter:

Option 1: Direct Connection through the TD100 Transmitter

Use alligator pins to connect the three wires inside the TD100 Transmitter.

```
Note:
Use this option if you haven't installed your TD100 Transmitter on top of your tank yet.
```

Option 2: Connection through the FINCH II – 6W

Use the adapter to connect to the circuit board in the FINCH II – 6W.

Connecting TD100 Transmitter to Computer

The **TD100 Transmitter** now needs to be connected to the computer that SensorLink is installed on. You can connect to your computer through a native COM Port or by using the provided USB serial port adapter.

- **1** Use one of the two options for connecting the **TD100 Transmitter** to your computer.
 - Option 1: Use the SV Bus Programming Kit to plug directly into a native COM Port on your computer
 - Option 2: Use USB Serial port adapter to plug into the SV Bus Programming Kit and then use the USB side to plug into your computer



Programming the TD100 Transmitter

1 Click **Program** from the top menu bar inside SensorLink.

🔶 Home	File	1 Program	₩ Read	Verify	🧾 Convert Units 🗼	Fir
Step 1: Probe Settings Probe Type					Steps 3, 4, and 5	
Coaxial Probe	÷	New Table				
		Depth (in)	Volume (US gal)	Information		_
Detection Mode 🔋		0.00	0.000	4mA Point		^
		1.00	1.000			
Performance	~	2.00	2.000			
Depth Units		3.00	3.000			
Inches		4.00	4.000			
		4.50	4.500	2Lo		
Volume Units		5.00	5.000			
Volume onno		6.00	6.000			
	~	7.00	7.000			
		7.50	7.500			
Step 2: Strapping Table		0.00	0.000	Call Laura		

The Program Strapping Table dialogue box appears.

	gram strapping to	able
elect COM Port		~
		× 🔝
COM Port not working? D	ownload Driver	
To program the strappin	ng table, you can fo	llow these steps:
1) Power OFF the TD Tra	ansmitter.	
2) Power ON the TD Tra	insmitter.	
3) Immediately click Pro	bgram button.	
- Progress		
- Progress		
- Progress		
— Progress ————		
— Progress —		
- Progress		
- Progress		
Progress	Cancel	Home

Tip:

If nothing appears in the **Select COM Port** drop-down menu, you will need to download and install the COM port driver that applies to how you connected the **TD100 Transmitter** to your computer.

This can be done by clicking the **Download Driver** link from this window.

2 Once the driver is downloaded, select the appropriate **COM Port** option from the drop-down menu.



3 Click the **push button switch** on the **SV Programming Kit** to power the **TD100 Transmitter** off and then back on.



- After the TD100 Transmitter is powered back on, click the Program button from the dialogue box in SensorLink.
 The progress bar will update and if everything runs successfully, your TD100 Transmitter is fully programed.
- 5 Click the **Home** button to return to the main screen.



FINCH II Programming

Titan Logix provides a FINCH II Programming Kit that includes the following four items:



Connecting to the FINCH II – 6W

The diagram below shows how the **USB-RS-232 Adapter** and the **RS-232 Adapter** connect to the FINCH II circuit board and to your computer.



- 1 Use the Titan Logix provided RS-232 Adapter to connect to the 5-pin connector on the FINCH II circuit board.
- 2 Then take the Titan Logix provided USB-RS-232 Adapter and connect this to the RS-232 Adapter.
- 3 Then connect the USB side of the USB-RS-232 Adapter to the computer that SensorLink is installed on.

Connecting FINCH II – 6W to Power Source

Use one of the two options to power on the FINCH II display.

Option 1: Wall Adapter Power Source

1 Use the Titan Logix provided Power Adapter and Transmitter to connect to a wall adapter.



Option 2: Vehicle Power Source

1 Refer to the TD100 System Installation Guide for instructions on connecting your FINCH II to your vehicle.



Programming FINCH II – 6W

1 Click **Finch II** from the main SensorLink page.

The Finch II Configuration window appears.

≡				Finch II Co	nfiguration	9	
Home	File Firmware						
Display Finch II		Select COM Po	ort	• 🔯	COM Por	rt not working? <u>Downlo</u>	ad the driver
Level Sensor				Compartm	ent Settings		
TD80		Finch II Model Number					
TD100		Enable RCM					
		Number of Compartmen	its to Enable				
				Alarm-Rela	y Mapping		
			Engine/AUX	Pump	Light	Horn	Bypass Alarm (ACK)

Tip:

If nothing appears in the **Select COM Port** drop-down menu, you will need to download and install the COM port driver that applies to how you connected the FINCH II to your computer.

This can be done by clicking the **Download the driver** link from this window.

2 Once the driver is downloaded, select the appropriate **Select COM Port** option from the drop-down menu.

Compartment Settings



- **3** Select the **Finch II Model Number** from the drop-down list.
 - **FINCH II:** Traditional 2-compartment display
 - FINCH II-W: 2-compartment display with Bluetooth capability
 - FINCH II 6W: 6-compartment display with Bluetooth capability



Model number appears on hardware cover

- 4 Select the **Enable RCM** checkbox if your installation includes a Rack Control Module. Leave this unselected if it does not apply.
- 5 Select the **Number of Compartments to Enable** from the drop-down menu that are applicable to your installation.

Based on your model selection and if using an RCM, the options within the drop-down list will update accordingly.

Alarm-Relay Mapping Configuration

Every FINCH II display leaves the factory with the same Alarm-Relay Mapping settings, as shown in the image. These default settings are the same for all three models of the FINCH II display.

You can modify these settings as they are applicable to the specific installation. To return to the factory settings, just click the **Set Defaults** button to return to the default state.

Alarm-Relay Mapping								
	Engine/AUX	Pump	Light	Horn	Bypass Alarm (ACK)			
Spill/Fail	\checkmark	\checkmark						
нн		\checkmark	\checkmark	\checkmark	\checkmark			
Fill				\checkmark	\checkmark			
Fall					\checkmark			
Relay Alarming State	Energized 🗸	De-energized v	Energized 🗸	Energized v				
	Set Defaults							

- **1** Select the boxes to enable or disable the specific alarms.
- 2 Select the drop-down menu under each column to configure if the alarm setting will be energized or de-energized when reached.



Tip:

It is recommended to contact Titan support if you need any further help.

Saving Configuration File

It is important to save the FINCH II- 6W configuration file for reference or troubleshooting purposes. Ensure the FINCH II is still connected and all fields are properly filled out before proceeding.

1 Click on the File > Save Configuration File from the upper left corner of the screen.



The Save As window appears.

- 2 Choose the desired location to save the strapping table to on your computer.
- 3 Fill out a File name (as per your organization's convention) for the configuration file and click Save.

Note: Notice that the file type is set to *.f2c format.

4 Click the **Program** button at the bottom of the screen.

		Compartme	ent Settings			
FINCH II-6W						
The company of the co						
 Enable RCM 						
Number of Compartmen	ts to Enable					
3 Compartments	~					
		Alarm-Rela	y Mapping			
	Projectation	Dama	11 alta	11.00	D	
	Engine/AUX	Pump	Light	Hom	Bypass Alarm (ACK)	
Spill/Fail	~					
HH		\checkmark		\checkmark	\checkmark	
Fill				\checkmark	~	
Fall					\checkmark	
Relay Alarming State	Energized .	De-energized v	Energized v	Energized 🗸		
Set Defaults						
					-	

A Confirmation notification appears in green text at the bottom left of the screen to confirm the programming was successfully accepted to the FINCH II – 6W.



Viewing FINCH II – 6W Configurations

Once your FINCH II is successfully programmed, you can go back afterwards to view the information if your FINCH II is still plugged into your computer. You can also import an existing FINCH II configuration file.

If importing or viewing your configuration of a FINCH II – 6W, ensure you have version 2.7x or later of the Firmware.

If viewing a configuration file from an older FINCH II model, only the Alarm-Relay Mapping settings will appear on the screen. Once the file is imported into SensorLink, go to **Programming FINCH II (Page 20)** to complete the other fields on this screen.

Note:

Any existing configurations filled out on this screen will be over-written with the new values.

Importing Configuration File

1 Click **File > Open Configuration File** from the upper left corner of the screen.

File	Firmware	
	Open Configuration File Save Configuration File	• 🔁
		Compa
	Finch II Model Number	

The **Open** dialogue window appears.

- 2 Navigate to the saved .f2c file and select the file.
- 3 Click **Open** to import this file into SensorLink.

The saved configuration file auto-populates on the screen.

4 Make any necessary changes and save your configuration file (Page 22).

Viewing Current Configuration

Prerequisite:

Ensure the FINCH II display is connected to your computer before proceeding.

1 From the Finch II Configuration window, click the Get Current Configuration button at the bottom of the screen.



The existing configuration of the connected FINCH II display auto-populates on the screen.

2 Make any necessary changes and save your configuration file (Page 22).